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Title: VIRTUAL PROTOTYPING AND TESTING FOR
MEDICAL DEVICE DEVELOPEMENT.

Applicant: Whirley and Chobotov
Serial No. 09/679,725 Filed: October 4, 2000
Our Docket No.: 24641-1070

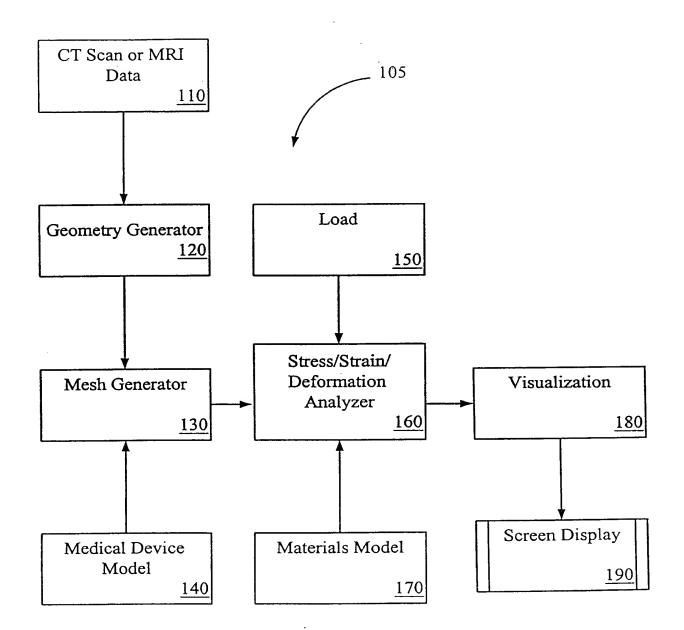
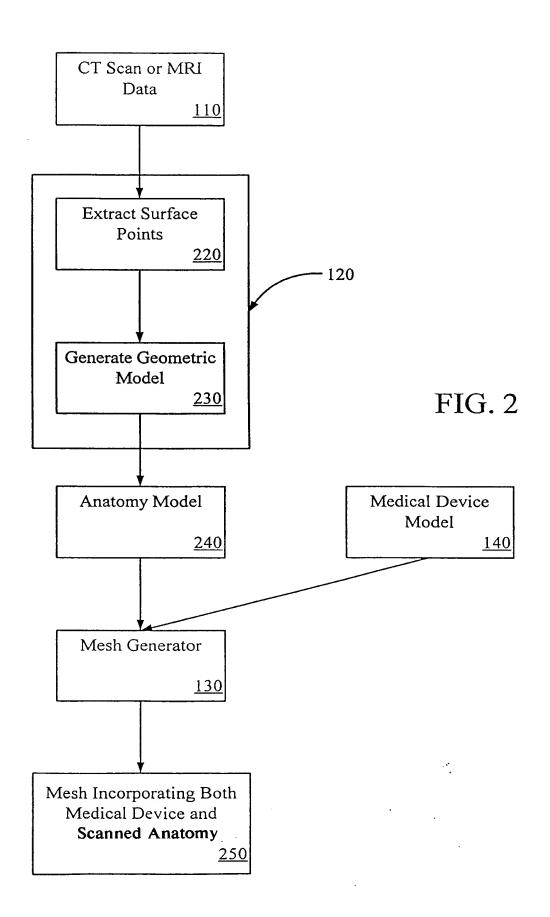


FIG. 1

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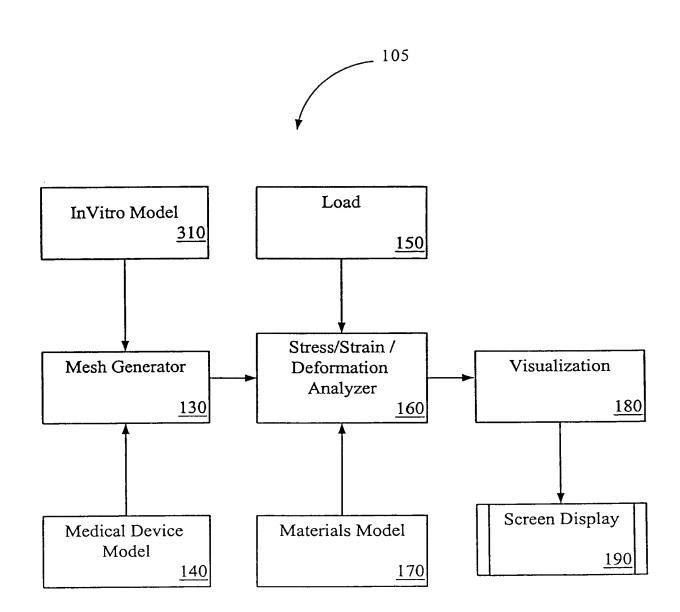
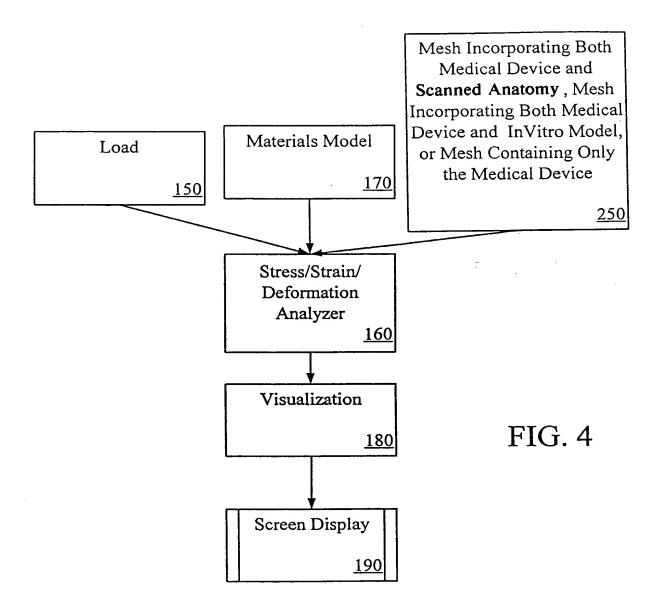


FIG. 3

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FIG. 5A

```
Line Command
    c *** Slotted Tube Integrated Stent Design Simulation: istent.run
2
       ----- parameter settings -----
3
4
    c .... inike=1 => make nike file; inike=0 => make dyna file
5
    c .... imodel = 0 => full 3 segment model with interconnects
6
7
             = 1 => 3-crown segment only
             = 2 => 6-crown segment only
8
    С
             = 3 => 12-crown segment only
9
     c \dots isym = 0 \Rightarrow full 360 deg model
10
             = 1 => symmetric model
11
     c .... isim_mode: type of simulation
12.
            = 1: => radial force to R f = X% R_0, restoring stress mat'l
13
            = 2: => flat plate force, restoring stress mat'l
14
            = 3: => predelivery compression, loading stress mat'l
15
            = 4: => initial expansion
16
            = 5: => frequency analysis
17
     c .... refine = X => add X elements via mseq in each direction
18
                   of the cross section
19
20
21
     parameter inike 1;
     parameter imodel 0;
22
23
     parameter isym 0;
     parameter isim mode 4;
24
25
     parameter refine 2;
26
                            c helps 'tighten' or stiffen spline
27
     para Tighten [0.9];
                     c range (0.5,1) (probably should not change)
28
29
      c ----- parameter settings -----
30
31
32
               ====== design parameters =
33
      c Note: Adjust specified OD for each segment considering the wall
 34
             thickness for that segment so that ID's match in a consistent
 35
             way for the tube blank from which they were cut.
 36
      С
 37
      c Upper segment --- 3 crowns
 38
 39
      c Middle segment -- 6 crowns
```

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FIG. 5B Line Command c Lower segment --- 12 crowns (conical) 41 c Parameters for 3-crown segment 42 43 44 para 45 RCyl3 [.5*2/25.4] dCIA3 [-.00] c delta of center of inner arc for 3 crown segment (-:0) 46 dCOA3 [0] c delta of center of outer arc for 3 crown segment (0:+) 47 c Circumferential width of segments for 3 crowns CW3 [.007] 48 RW3 [.005] c Radial width for 3 crowns 49 NRA3 [.0095] c normal radius of smaller cylinders (arcs) 50 c for 3 crowns 51 Ht3 [0.224] c distance from center of upper arcs 52 c to center of lower arcs for 3 crowns 53 NLegEl3 [12]; c number of elements along the leg 54 55 56 c Parameters for 6-crown segment 57 58 С 59 para RCyl6 [.5*2/25.4] c outside radius for 6 crown segment 60 c delta of center of inner (smaller) arc for 6 crown 61 dCLA6 [0] segment(-:0) dCOA6 [0.002] c delta of center of outer (larger) arc for 6 crown 62 segment (0:+) c Circumferential width of segments for 6 crowns 63 CW6 [.009] c Radial width for 6 crowns 64 RW6 [.009] NRA6 [.0105] c normal radius of smaller cylinders (arcs) 65 c for 6 crowns 66 c distance from center of upper arcs 67 Ht6 [.115] c to center of lower arcs for 6 crowns 68 NLegEl6 [12]; c number of elements along the leg 69 70 71 c Parameters for 12-crown segment 73 С 74 para c delta of center of inner arc for 12 crown segment (-:0) dCIA12 [0] 75

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FIG. 5C

```
Line Command
                         c delta of center of outer arc for 12 crown segment
76
        dCOA12 [0]
                               (0:+)
                         c Circumferential width of segments for 12 crowns
        CW12 [.005]
77
        RW12 [.008]
                         c Radial width for 12 crowns
78
                           c normal radius of smaller cylinders (arcs)
        NRA12 [.006]
79
                    c for 12 crowns
80
                         c distance from center of upper arcs
81
        Ht12 [.050]
                    c to center of lower arcs for 12 crowns
82
                    c (measured along the leg, not necessarily in
83
                    c the z direction)
84
        c first outside radius for 12 crown segment (near other segments)
85
        RCyl12_1 [.5*2/25.4 - (.016-%RW12)]
86
        c second outside radius for 12 crown segment (bottom)
87
        RCYl12 2 [.5*1.4/25.4 - (.016-%RW12)]
88
89
     С
        NLegEl12 [10]; c number of elements along the leg
90
91
92
     С
     c Interconnects
93
94
     С
95
96
97
      c Upper interconnects
98
                          c height of interconnect
99
      para HIUp [.02]
                          c fillet radius for blend
          FRUp [.005]
100
                           c circumferential width
          [.006] [CWUp
101
                            c radial width at 3-crown end
          IRWUp3 [.005]
102
          IRWUp6 [.006]; c radial width at 6-crown end
103
 104
 105
       C
       c S-interconnects
 106
 107
                          c vertical distance between upper or lower arc centers
 108
       para SIVer [.01]
                    c also the distance from the vertical mid-line to
 109
                    c the first arc center
 110
          SIHor [.010] c horizontal distance between upper two or
 111
                    c lower two arc centers
 112
          SIr [.004] c arc radius
 113
```

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FIG. 5D

```
Line
      Command
         SIrO [%SIr+%ICWUp/2] c outer radius
114
115
         SIrI [%SIr-%ICWUp/2]; c inner radius
116
117
118
      c Lower interconnects
119
120
      para HILr [.031] c height of interconnect
121
         FRLr [.010] c fillet radius for blend
122
         ICWLr [.007] c circumferential width
123
        IRWLr6 [.005] c radial width at 6-crown end
        IRWLr12 [.005]; c radial width at 12-crown end
124
125
126
      С
127
                    = design parameters
128
129
      c .... set cylinder ID & OD for compression
130
131
      if (%isim_mode.le.3) then
132
      parameter ricompcyl
       [1.1*max(%RCyl3,%RCyl6,%RCyl12_1,%RCyl12_2)];
133
      parameter rocompcyl
        [1.4*max(%RCyl3,%RCyl6,%RCyl12 1,%RCyl12 2)];
134
135
      c .... set cylinder ID & OD for expansion
136
137
      elseif (%isim_mode.eq.4) then
138
      parameter rocompcyl
        [0.95*(min(%RCyl3,%RCyl6,%RCyl12 1,%RCyl12 2)-%RW6)];
139
      parameter ricompcyl
        [0.7*(min(%RCyl3,%RCyl6,%RCyl12 1,%RCyl12 2)-%RW6)];
140
      endif
141
      С
142
      C
143
      c Materials assignments
144
145
      parameter matst12 3;
146
     parameter matst6 4;
147
      parameter matst3 5;
```

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FIG. 5E

```
Line Command
      parameter mati126 6;
148
149
      parameter mati63 7;
150
151
152
      if (%isim_mode.eq.1) then
        echo *** Radial Force Simulation ***
153
      elseif (%isim mode.eq.2) then
154
        echo *** Flat Plate Force Simulation ***
155
      elseif (%isim mode.eq.3) then
156
        echo *** Predelivery Compression Simulation ***
157
      elseif (%isim mode.eq.4) then
158
        echo *** Initial Expansion Simulation ***
159
      elseif (%isim mode.eq.5) then
160
        echo *** Natural Frequency Analysis ***
161
162
      else
163
        echo !!! ERROR: illegal isim_mode !!!
        interrupt
164
      endif
165
166
167
      c ----- analysis options -----
      title stent initial expansion simulation
168
169
          *** DYNA3D Analysis Options ***
170
171
172
      if (%inike.eq.0) then
       echo Making DYNA3D input file
173
174
       dyna3d
        dynaopts
175
        term 5.0e-5
176
        plti 1.e-6
177
178
        prti 5.0e-6
179
180
      c .... DR options
181
182
       itrx 500
       tolrx 1.0e-2
183
184
       drdb
185
      c .... thermal effects option - temp from load curve 1
186
```

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FIG. 5F

```
Line Command
187
      С
188
       teo 1
189
190
      tssf 0.0
191
192
      c print initial time step size
193
194
      c prtflg 1
195
196
      c .... turn off (0) or on (1) SAND database flag
197
198
       edsdf 0
199
200
       nrest 90000
201
       nrunr 95000;
202
      c .... DYNA3D discrete nodes impacting surface - stent to cyl
203
204
                  * one side (180 deg) *
205
206
      sid 1 dni
207
      c sfif
208
      c mfif
209
      pnlts 1.0e-0
210
      pnltm 1.0e-0
211
212
213
      c .... DYNA3D discrete nodes impacting surface - stent to cyl
214
                  * opposite side *
215
216
      c sid 2 dni
217
      c sfif
218
      c mfif
219
      c pnlts 1.0e-4
220
      c pnltm 1.0e-4
221
      c ;
222
223
      c .... end DYNA3D commands
224
225
      endif
```

MEDICAL DEVICE DEVELOPEMENT.

```
Line Command
                                                              FIG. 5G
226
      С
227
          *** NIKE3D Analysis Options ***
228
      С
229
230
      if (%inike.eq.1) then
       echo Making NIKE3D input file . . .
231
232
       nike3d
233
       nikeopts
234
        nstep 5
235
        delt 0.2
236
        anal stat
237
238
      c .... step tol of 1e-8 seems OK for predel compression
239
240
      if (%isim_mode.eq.1.or.%isim_mode.eq.2) then
241
        dctol -1.0e-8
      elseif (%isim_mode.eq.3) then
242
243
        dctol -1.0e-6
244
      endif
245
246
      c .... max iterations per stiffness reform
247
        nibsr 20
248
249
250
      c .... max stiffness reforms per step
251
252
        msrf 20;
253
254
       c .... temperatures follow load curve 1
           ** manually add tref=1.0 on matl 2 control card cols 26-35 **
255
256
257
        teo 1
258
       if (%isim mode.eq.1.or.%isim mode.eq.2) then
259
       elseif (%isim mode.eq.3.or.%isim mode.eq.4) then
260
261
        iprt 25
262
       endif
263
        iplt 1
        nsbrr 1
264
```

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Line Command 265 stifcore 1 FIG. 5H 266 bfgscore 267 bwmo new 268 echo Bandwidth minimization ACTIVATED with "NEW" option 269 270 c element constitutive data incore 271 272 bfor 10 273 sfor 10 274 bef 11 275 c linear solver 276 277 Isolver fissle 278 279 280 c solid element stent contact surface 281 282 sid 1 sv 283 284 if (%isim mode.eq.1) then 285 286 287 pnlt 1.0e-5 288 elseif (%isim mode.eq.2) then 289 pnlt 0.00001 290 elseif (%isim mode.eq.3) then 291 292 c essential to adjust penalty 293 294 pnlt 1.0e+4 elseif (%isim mode.eq.4) then 295 296 pnlt 1.0e-5 297 c iaug 1; 298 endif 299 300 301 c slidesurface between interconnects and segments 302

sid 2 tied

303

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```
Line
      Command
304
                                                                 FIG. 5I
305
      С
      c .... NIKE3D shell geometric stiffness (HL only)
306
307
308
       segs 1;
309
      c .... end NIKE3D section
310
311
312
      endif
313
314
      c .... symmetry planes
315
316
      if (%isym.eq.1) then
317
318
      c .... Symmetric Model
           theta=-60 and +60 symmetry to remove rigid body modes
319
320
      С
321
      c plane 1
      c 0.0 0.0 0.0
322
323
      c [-\sin(60)][-\cos(60)]0.0
324
          0.0005 symm;
325
       c plane 2
326
       c 0.0 0.0 0.0
       c [-\sin(60)][\cos(60)]0.0
327
328
           0.0005 symm;
329
       С
330
       else
331
       c .... symmetry planes to remove rigid body modes for full model
332
333
334
       plane 1
335
        0.0 0.0 0.0
336
        1.0 0.0 0.0
337
         .0005 symm;
338
       plane 2
 339
        0.0 0.0 0.0
        0.0 1.0 0.0
 340
 341
         .0005 symm;
       c plane 3
 342
```

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```
Line Command
      c 0.0 0.0 0.0
343
                                                               FIG. 5J
      c 0.0 0.0 TBD
344
345
          .0005 symm;
346
      endif
347
      С
348
      if (%inike.eq.0) then
349
350
      c .... Load Curves for DYNA3D **ADD DR FLAG TO INPUT FILE **
351
352
353
      if (%isim_mode.eq.1) then
354
355
      c .... radial force
356
357
      lcd 1
358
         0.000E+00 1.000E+00
359
         7.500E-03 2.250E+04
         1.000E-00 2.250E+04;
360
      c 1.000E-02 3.000E+04
361
362
      c 1.000E-00 3.000E+04;
363
      elseif (%isim mode.eq.2) then
364
      c .... flat plate compression, lcd 1 not used (dummy definition)
365
366
      С
367
      quit
368
369
      elseif (%isim mode.eq.3) then
370
371
      c .... predelivery compression strain
372
373
      lcd 1
374
         0.000E+00 1.000E+00
375
         1.000E-02 2.008E+05
376
         1.000E-00 2.008E+05;
377
      endif
378
379
      c .... load curve #2 only used for flat plate compression
380
      С
381
      lcd 2
```

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```
Line Command
382
        0.000E+00 0.000E+00
        1.000E+00 0.000e-00;
383
384
      endif
385
386
      if (%inike.eq.1) then
387
      c .... ****** Load Curves for NIKE3D *******
388
389
390
      if (%isim mode.eq.1) then
391
392
      c .... radial force
393
394
      lcd 1
395
         0.000E+00 1.000E+00
396
         1.000E+00 2.000E+03;
397
      elseif (%isim mode.eq.2) then
398
399
      c .... flat plate compression
400
401
      lcd 1
402
         0.000E+00 1.000E+00
403
          1.000E+00 0.000E+00;
404
      elseif (%isim_mode.eq.3) then
405
406
      c .... predelivery compression strain
407
408
      lcd 1
         0.000E+00 1.000E+00
409
          1.000E+00 2.008E+03;
410
411
      elseif (%isim mode.eq.4) then
412
413
      c .... initial expansion strain
414
415
      lcd I
      c .... thermal load (activate TEO above)
416
417
      c 0.000E+00 1.000E+00
418
          1.000E+00 -2.008E+04;
419
      c .... prescribed displacement
420
          0.000E+00 0.000E+00
```

FIG. 5K

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```
Command
Line
         1.000E+00 1.000E-02;
421
                                                                FIG. 5L
422
      endif
423
      С
424
      c ----- stent parts -----
425
426
      include irss.tg
427
428
      c ----- stent materials -----
429
430
      if (%inike.eq.1) then
           if (%isim_mode.eq.1.or.%isim_mode.eq.2) then
431
432
              include istent.mats_nike_solid
              echo model for radial force/flat plate analysis
433
434
           elseif (%isim mode.eq.3) then
435
              include istent.mats_compress_nike_solid
              echo model for predelivery compression strain
436
           elseif (%isim mode.eq.4) then
437
438
              include istent.mats compress_nike_solid
439
              echo model for initial expansion strain
440
           endif
441
442
      elseif (%inike.eq.0) then
           if (%isim mode.eq.1.or.%isim mode.eq.2) then
443
              include istent.mats dyna_solid
444
              echo model for radial force/flat plate analysis
445
446
           elseif (%isim_mode.eq.3) then
              include istent.mats compress dyna_solid
447
              echo model for predelivery compression strain
448
            elseif (%isim mode.eq.4) then
449
              include istent.mats compress_dvna_solid
450
451
              echo model for initial expansion strain
452
            endif
453
      endif
454
      С
      c .... cylindrical compression for radial force or predelivery compression
455
456
      if (%isim mode.eq.1.or.%isim mode.eq.3.or.%isim_mode.eq.4) then
457
458
459
         if (%isym.eq.1) then
```

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Line	Command
460	include cylinder.parts_sym
461	else
462	include cylinder.parts
463	endif
464	c
465	if (%inike.eq.1) then
466	include cylinder.materials_nike
467	elseif (%inike.eq.0) then
468	include cylinder.materials_dyna
469	endif
470	endif
471	c
472	stp .01
473	merge
171	C

FIG. 5M

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```
****** TPEG Inflatable Proximal Seal Simulation ***********
1
2
                        (seal.run)
       С
                                                                           FIG. 6A
                        March, 1999
3
       С
4
5
       c ----- parameter settings -----
6
7
       c .... analytical model aorta geometric parameters
8
             (distortion is 4-lobe)
9
       С
10
       parameter r aorta [10.0/25.4];
11
       parameter thk aorta [1.0/25.4];
       parameter amp_plaque [0.0/25.4];
12
13
14
       parameter ro_aorta [%r_aorta+%thk_aorta];
15
16
       c .... -- TPEG Design Parameters --
17
18
       parameter r tpeg [10/25.4];
19
       parameter r_ps [3/25.4];
       parameter l_tpeg 2.0;
20
21
       parameter 1_flap 0.25;
22
23
       parameter graft wall thick [6*0.0013];
       parameter cuff_wall_thick [3*0.0013];
24
25
       parameter flap wall thick [6*0.0013];
26
       С
27
28
       c .... Pressures and load curve assignments
29
30
       parameter P_hemo 2.32;
       parameter P cuff 3.0;
31
32
33
       parameter lc_hemo 1;
34
       parameter lc proxcuff 3;
35
36
       c .... TPEG folding simulation parameters
37
       parameter vel fold 20.0;
38
39
       parameter t fold [0.25/%vel fold];
40
       parameter t_init 0.0e-3;
41
       С
42
       С
```

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```
43
       c ----- analysis options -----
       title sc6.i Seal CT-Solid r_t=10mm r_ps=3mm P_cuff=3.0990428
44
45
46
            *** DYNA3D Analysis Options ***
       С
                                                                    FIG. 6B
47
       С
48
       dyna3d
49
       dynaopts
        term 6.5e-2
50
51
        plti 5.e-4
52
        prti 2.5e-2
53
54
       c .... DR options
55
56
       itrx 500
57
58
       c .... increase DR tol to prevent convergence after compression before expansion
59
60
       c tolrx 1.0e-6
61
       tolrx 1.0e-12
62
       drdb
63
64
        tssf 0.9
65
66
       c .... turn off (0) or on (1) SAND database flag
67
       С
68
         edsdf 0
69
70
        nrest 90000
        nrunr 5000;
71
72
73
       c .... symmetry planes on xz and yz planes
74
75
       plane 1
76
         0.0 0.0 0.0
77
         1.0 0.0 0.0
                     0.001 symm;
78
       plane 2
79
         0.0 0.0 0.0
        0.0 1.0 0.0 0.001 symm;
80
81
82
       c .... DYNA3D slidesurface: +x folder cylinder
83 .
       sid 1 sv
84
```

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Title: VIRTUAL PROTOTYPING AND TESTING FOR
MEDICAL DEVICE DEVELOPEMENT.

Applicant: Whiley and Chobotov
Serial No. 09/679,725 Filed: October 4, 2000
Cur Docke: Pic.: 24641-1070

```
85
       pnlts 1.0
                                                                FIG. 6C
86
       pnltm 1.0
87
        pen
88
89
90
        c .... DYNA3D slidesurface: -x folder cylinder
91
        С
92
        sid 2 sv
93
       pnlts 1.0
94
       pnltm 1.0
95
       pen
96
97
        С
98
99
        c .... DYNA3D slidesurface: +y folder cylinder
100
101
        sid 3 sv
102
       pnlts 1.0
103
       pnltm 1.0
104
        pen
105
106
107
        c .... DYNA3D slidesurface: -y folder cylinder
108
109
        sid 4 sv
110
        pnlts 1.0
111
        pnltm 1.0
112
        pen
113
114
115
        c .... DYNA3D tpeg to aorta (aorta is master)
116
        С
117
        sid 5 sv
118
119
        c .... solid element aorta
120
121
        pnlts 0.1
122
        pnltm 0.1
123
124
        c .... shell element aorta
125
126
        c pnlts 1.0
```

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```
127
       c pnltm 1.0
                                                                       FIG. 6D
128
       pen
129
       ;
130
       c .... load curve: hemodynamics **** ADD DR FLAG TO INPUT FILE ****
131
132
133
       lcd 1
134
        0.000E+00
                            0.000E+00
135
        [%t init+2*%t fold+1.0e-3] 0.000e+00
136
        [%t init+2*%t_fold+2.0e-3] %P_hemo
137
        1.000E+00
                            %P_hemo;
138
       С
139
       c .... load curve: channel !! NOT USED !! **** ADD DR FLAG TO INPUT FILE ****
140
141
       lcd 2
142
        0.000E+00 0.000E+00
143
        [%t init+2*%t_fold+1.0e-3] 0.000e+00
144
        [%t init+2*%t_fold+2.0e-3] 0.000e-00
        1.000E+00
145
                             0.000e-00;
146
       c .... load curve: proximal cuff **** ADD DR FLAG TO INPUT FILE ****
147
148
       C
149
       lcd 3
150
        0.000E+00 0.000E+00
151
        [%t init+2*%t fold+1.0e-3] 0.000e+00
152
        [%t_init+2*%t_fold+2.0e-3] %P_cuff
153
        1.000E+00
                             %P_cuff;
154
       c .... load curve for +x folder cylinder motion/velocity
155
156
157
       lcd 4
        0.000E+00
                              0.000E+00
158
                            0.000E+00
159
        %t init
160
                                 [-%vel fold]
        [%t_init+1.0E-04]
                                 [-%vel_fold]
161
        [%t_init+%t_fold]
162
                                    0.000E+00
        [%t init+%t_fold+1.0e-3]
163
        [%t init+2*%t fold+1.0e-3]
                                     0.000e+00
164
        [%t_init+2*%t_fold+2.0e-3]
                                     [2.0*%vel fold]
165
        [%t_init+3*%t_fold+2.0e-3]
                                     [2.0*%vel fold]
166
                                     0.000e+00
        [%t init+3*%t fold+3.0e-3]
167
        1.000E+00
                        0.000E+00;
168
       ¢
```

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```
c .... load curve for -x folder cylinder motion
 169
                                                              FIG. 6E
 170
        С
 171
        lcd 5
 172
         0.000E+00
                                 0.000E+00
                              0.000E+00
 173
         %t init
         [%t init+1.000E-04]
                                    [ %vel_fold]
 174
         [%t_init+%t fold]
                                   [%vel fold]
 175
         [%t_init+%t_fold+1.0e-3]
                                      0.000E+00
 176
 177
         [%t_init+2*%t_fold+1.0e-3]
                                       0.000e+00
         [%t init+2*%t_fold+2.0e-3]
                                       [-2.0*%vel fold]
 178
                                       [-2.0*%vel_fold]
 179
         [%t_init+3*%t_fold+2.0e-3]
                                       0.000e+00
 180
         [%t init+3*%t fold+3.0e-3]
                                 0.000E+00;
 181
          1.000E+00
 182
 183
        c .... load curve for +y folder cylinder motion
 184
 185
        lcd 6
          0.000E+00
                                 0.000E+00
 186
          %t_init
                               0.000E+00
 187
          [%t init+1.000E-04]
                                    [-%vel_fold]
 188
          [%t_init+%t fold]
                                   [-%vel fold]
 189
 190
          [%t init+%t fold+1.0e-3]
                                      0.000E+00
                                       0.000e+00
.. 191
          [%t init+2*%t fold+1.0e-3]
          [%t init+2*%t fold+2.0e-3]
                                       [2.0*%vel fold]
 192
                                       [2.0*%vel fold]
 193
          [%t_init+3*%t_fold+2.0e-3]
 194
          [%t init+3*%t fold+3.0e-3]
                                       0.000e+00
          1.000E+00
                                 0.000E+00;
 195
 196
         C
 197
         c .... load curve for -y folder cylinder velocity
 198
         С
 199
         lcd 7
                                 0.000E+00
 200
          0.000E+00
                               0.000E+00
 201
          %t init
                                    [%vel fold]
          [%t init+1.000E-04]
 202
                                   [ %vel_fold]
 203
          [%t init+%t fold]
          [%t_init+%t_fold+1.0e-3]
                                      0.000E+00
 204
          [%t init+2*%t fold+1.0e-3]
                                        0.000e+00
 205
         [%t init+2*%t_fold+2.0e-3]
                                       [-2.0*%vel fold]
 206
          [%t init+3*%t fold+2.0e-3]
                                        [-2.0*%vel fold]
 207
          [%t_init+3*%t_fold+3.0e-3]
                                        0.000e+00
 208
 209
          1.000E+00
                                 0.000E+00:
 210
```

С

6F

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211	c parts and materials	
212	c	FIG.
213	c	
214	c get CT-data meshed aorta; convert cm to inches	
215	c	
216	csca [1./2.54]	
217	include tpeg.part_ct_aorta3	
218	c	
219	csca 1.0	
220	c	
221	c option for analytical aorta model	
222	c	
223	c include tpeg.part_eq_aorta	
224	c	
225	include tpeg.part_cuffl	
226	include tpeg.part_folder2	
227	c	
228	include tpeg.materials_dyna	
229	C	
230	c use negative tols to prevent aorta nodes merging w/ folder cylinder	•
231	c nodes if they coincidently become adjacent	
232	C	
233	c merge nodes within CT aorta part using rather loose tolerance	
234	C	
235	bptol 1 1 0.01	
236	bptol 1 3 -1.0	
237	bptol 1 4 -1.0	
238	bptol 1 5 -1.0	
239	bptol 1 6 -1.0	
240	tp .001	
241	C	

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```
1
         С
                                                                           FIG. 7A
2
         С
                     tpeg.part_ct_aorta3
3
                      April 15, 1999
         С
4
         С
5
         С
           ----- Aortic Model for Inflatable TPEG Model -----
6
                  Derived from Patient CT Data
         Ç
7
         С
                  Outer surface constructed with 0.52 mm offset from inner
8
         С
9
         c .... this is an aortic mesh file which surrounds the neck of the
10
              3-D AAA reconstruction with solid elements.
11
         C
12
         С
              This file uses TrueGrid planes, oriented by eye using trial
13
              and error graphically, to determine an orthonormal section.
         С
14
              Trick there is to adjust surface until walls of proximal neck section
         С
15
              are parallel to global z axis. Use rz to rotate screen to find values,
         С
16
              then use in surface transformation to position CT data for meshing.
         С
17
18
         c .... import IGES file containing surface data from CT scan
19
20
         iges solid1.igs 1 1 mx -18.54 my -16.8 ry 24 rx 22 mz 4.8;
21
22
         c .... inner surface
23
24
         sd 17 sds 9 12;
25
         С
26
         c .... outer surface
27
28
         sd 18 sds 15 16;
29
30
         sd 201 plan
31
             0.0.1.5
             0 0 1
32
33
         sd 202 plan
34
             0.0.2.5
35
             0 0 1
36
         sd 203 plan
37
             0.0.-2.3
38
             0 0 1 -
39
         sd 204 plan
40
             0.0.3.3
41
             0 0 1
```

42

sd 301 cy 0 0 0 0 0 1 1.35

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```
sd 401 plan
43
                                                                     FIG. 7B
             0.0.0.
44
             0.1.0.
45
46
         С
         c .... adjust mz to position part at cuff on Z-axis;
47
                cuff may be z=[2,2.15]
48
         cylinder
49
50
          12;
51
         1 2 3;
         1234;
52
53
         С
         1.0 1.25
54
         0 180.0 360.0
55
         -2.3 1.5 2.5 3.3
56
57
58
         mseq i 2
         mseq j 29 29
59
60
         mseq k 20 5 5
61
         c .... project top and bottom ends of aorta segment onto orthonormal planes
62
63
64
         sfi;;-2; sd 201
         sfi;;-3; sd 202
65
66
          c .... project top of upper neck segment onto orthonormal plane
67
68
69
          sfi;;-4; sd 204
70
          c .... project bottom of lower neck segment onto orthonormal plane
71
               after radially expanding bottom ring by delta-r=2.0
72
          mbi -1;; -1; x 2.0
73
74
          mbi -2;; -1; x 2.0
          sfi;;-1; sd 203
75
76
          c .... project inner cylinder surface onto aorta luminal surface
77
78
79
          sfi -1; 1 3; 2 3; sd 17
          sfi -1; 1 3; 3 4; sd 17
80
          sfi -1; 1 3; 1 2; sd 17
81
82
          c .... project outer cylinder onto aorta outer wall surface
 83
 84
```

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```
85
         sfi -2; 1 3; 2 3; sd 18
86
         sfi -2; 1 3; 3 4; sd 18
87
         sfi -2; 1 3; 1 2; sd 18
88
89
         c .... project theta=0/360 seam onto a plane to facilitate merging
90
91
         sfi 1 2; -1; ; sd 401
         sfi 1 2; -3; ; sd 401
92
93
94
95
         c ... --- slidesurface definition with TPEG body ---
96
97
         orpt + 0.0.3.0
98
         sii -1; 1 3; 3 4; 5 m
99
100
         c .... +y hemicylinder is material 11; -y is mat 12
101
102
         mti; 12; 24; 11
         mti; 23; 24; 12
103
104
105
         c .... rigid material for aneurysm sac
106
107
         mti; 13; 12; 13
108
109
         c .... Boundary Conditions
110
              * fix proximal end only in z
111
112
         bi;;-4; dz 1;
113
         c .... adjust mz to position aorta at cuff on Z-axis;
114
115
                cuff may be z=[2,2.15]
116
          lct 1
117
             mz [1.01*2.54] mx 0.7;;
118
          lrep 1;
         endpart
119
120
```

FIG. 7C

MEDICAL DEVICE DEVELOPEMENT.
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FIG. 8A

```
c ****** Slotted Tube Integrated Stent Design Simulation ******
1
2
                      (istent.run)
       С
3
              Stent design analysis & CT-Anatomy simulation
       С
4
5
       c ----- parameter settings -----
6
7
        c .... inike=1 => make nike file; inike=0 => make dyna file
8
       c .... imodel = 0 => full 3 segment model with interconnects
9
       c = 1 \Rightarrow 3-crown segment only
                = 2 => 6-crown segment only
10
11
              = 3 => 12-crown segment only
        c \dots isym = 0 \Rightarrow full 360 deg model
12
              = 1 => symmetric model
13
       c .... isim_mode: type of simulation
14
15
              = 1: => radial force to R f = 80% R 0, restoring stress mat'l
              = 2: => flat plate force, restoring stress mat'l
16
17
              = 3: => predelivery compression to 12 F, loading stress mat'l
       С
18
              = 4: => initial expansion
       С
              = 5: => frequency analysis
19
20
              = 6: => anatomy deployment
        c .... refine = X => add X elements via mseq in each direction
21
                    of the cross section
22
23
24
        c!!! warning - only 1st 8 characters of variable unique!!!!
25
26
        parameter inike 1;
27
        parameter imodel 2;
28
        parameter isym 0;
29
        parameter isim mode 6;
30
        parameter refine 1;
31
32
        para Tighten [0.9];
                             c helps 'tighten' or stiffen spline
33
                       c range (0.5,1) (probably should not change)
34
35
        c ----- parameter settings -----
36
37
        c .... design parameters
38
        c Note: Adjust specified OD for each segment considering the wall thickness
39
40
              for that segment so that ID's match in a consistent way for the
41
              tube blank from which they were cut.
        С
42
43
        c Upper segment --- 3 crowns
44
        c Middle segment -- 6 crowns
45
        c Lower segment --- 12 crowns (could be conical)
46
47
        c Parameters for 3-crown segment
48
49
        para
```

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FIG. 8B

```
50
         RCyl3 [29*0.5/25.4]
51
           dCIA3 [-.00] c delta of center of inner arc for 3 crown segment (-:0)
                         c delta of center of outer arc for 3 crown segment (0:+)
52
           dCOA3 [0]
           CW3 [.020]
                         c Circumferential width of segments for 3 crowns
53
           RW3 [.018] c Radial width for 3 crowns
54
55
           NRA3 [.0195] c normal radius of smaller cylinders (arcs)
56
                    c for 3 crowns
57
           Ht3 [1.048] c distance from center of upper arcs
58
                    c to center of lower arcs for 3 crowns
59
           NLegEl3 [12]; c number of elements along the leg
60
        c Parameters for 6-crown segment
61
62
63
        para
           RCyl6 [29*0.5/25.4] c outside radius for 6 crown segment
64
                        c delta of center of inner (smaller) arc for 6 crown segment (-:0)
65
           dCIA6 [0]
           dCOA6 [0.005] c delta of center of outer (larger) arc for 6 crown segment (0:+)
66
           CW6 [.020] c Circumferential width of segments for 6 crowns
67
           RW6 [.018] c Radial width for 6 crowns
68
69
           NRA6 [.0195] c normal radius of smaller cylinders (arcs)
70
                    c for 6 crowns
                         c distance from center of upper arcs
71
72
                    c to center of lower arcs for 6 crowns
73
           NLegEl6 [12]; c number of elements along the leg
74
75
        c Parameters for 12-crown segment
76
77
        рага
                           c delta of center of inner arc for 12 crown segment (-:0)
78
           dCIA12 [0]
                            c delta of center of outer arc for 12 crown segment (0:+)
79
           dCOA12 [0]
                             c Circumferential width of segments for 12 crowns
80
           CW12 [.008]
                             c Radial width for 12 crowns
81
           RW12 [.008].
82
           NRA12 [.006]
                              c normal radius of smaller cylinders (arcs)
                       c for 12 crowns
83
84
                            c distance from center of upper arcs
           Ht12 [.164]
                       c to center of lower arcs for 12 crowns
85
                       c (measured along the leg, not necessarily in
86
87
                       c the z direction)
88
           c first outside radius for 12 crown segment (near other segments)
89
           RCyl12_1 [22*0.5/25.4]
90
           c second outside radius for 12 crown segment (bottom)
91
           RCY112 2 [20*0.5/25.4]
92
93
           NLegEl12 [10]; c number of elements along the leg
94
95
        c Interconnects
96
97
        c Upper interconnects
98
```

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```
99
        para
                                                                       FIG. 8C
        c HIUp [.10]
100
                         c height of interconnect
           HIUp [.20]
                          c height of interconnect
101
           FRUp [.016] c fillet radius for blend
102
           ICWUp [.010] c circumferential width
103
          IRWUp3 [.016] c radial width at 3-crown end
104
105
           IRWUp6 [.016]; c radial width at 6-crown end
106
107
        c S-interconnects
108
109
        para
           SIVer [.03]
                         c vertical distance between upper or lower arc centers
110
                         c vertical distance between upper or lower arc centers
111
           SIVer [.06]
                    c also the distance from the vertical mid-line to
112
                    c the first arc center
113
114
           SIHor [.0125] c horizontal distance between upper two or
115
                    c lower two arc centers
116
           SIr [.008] c arc radius
           SIrO [%SIr+%ICWUp/2] c outer radius
117
           SIrI [%SIr-%ICWUp/2]; c inner radius
118
119
120
        c Lower interconnects
121
        рага
122
        c HILr [.071] c height of interconnect
           HILr [.142] c height of interconnect FRLr [.016] c fillet radius for blend
123
124
           ICWLr [.016] c circumferential width
125
           IRWLr6 [.005] c radial width at 6-crown end IRWLr12 [.005]; c radial width at 12-crown end
126
127
128
129
        c .... design parameters =
130
131
        c .... set cylinder ID & OD for compression
132
133
        if (%isim mode.le.3.or.%isim mode.eq.6) then
        parameter ricompcyl [1.1*max(%RCyl3,%RCyl6,%RCyl12_1,%RCyl12_2)];
134
        parameter rocompcyl [1.4*max(%RCyl3,%RCyl6,%RCyl12 1,%RCyli2 2)];
135
136
137
        c .... set cylinder ID & OD for expansion
138
139
        elseif (%isim mode.eq.4) then
        parameter rocompcyl [0.95*(min(%RCyl3,%RCyl6,%RCyl12_1,%RCyl12_2)-%RW6)];
140
        parameter ricompcyl [0.7* (min(%RCyl3,%RCyl6,%RCyl12_1,%RCyl12_2)-%RW6)];
141
142
143
        C
144
        c Materials assignments
145
146
        parameter matst12 3;
147
        parameter matst6 4;
```

FIG. 8D

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```
148
       parameter matst3 5;
149
       parameter mati126 6;
150
       parameter mati63 7;
151
152
       if (%isim mode.eq.1) then
          echo *** Radial Force Simulation ***
153
154
       elseif (%isim_mode.eq.2) then
155
          echo *** Flat Plate Force Simulation ***
156
       elseif (%isim_mode.eq.3) then
          echo *** Predelivery Compression Simulation ***
157
158
       elseif (%isim_mode.eq.4) then
159
          echo *** Initial Expansion Simulation ***
       elseif (%isim_mode.eq.5) then
160
161
          echo *** Natural Frequency Analysis ***
       elseif (%isim mode.eq.6) then
162
163
          echo *** Anatomy Deployment Simulation***
164
       else
          echo !!! ERROR: illegal isim mode !!!
165
166
          interrupt
       endif
167
168
169
        c ----- analysis options -
170
        title human-size stent anatomy deployment
171
           *** DYNA3D Analysis Options ***
172
        С
173
174
        if (%inike.eq.0) then
175
        echo Making DYNA3D input file
176
        dyna3d
177
         dynaopts
178
         term 2.0e-4
179
         plti 1.e-4
180
         prti 5.0e-6
181
182
        c .... DR options
183
184
        c itrx 500
185
        c tolrx 1.0e-6
        c drdb
186
187
188
        c .... thermal effects option - temp from load curve 1
189
190
        if (%isim_mode.ne.5) then
191
        teo 1
192
        endif
193
        С
194
        tssf 0.0
195
196
        c print initial time step size
```

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```
197
        С
                                                                       FIG. 8E
198
        c prtflg 1
199
200
        c .... turn off (0) or on (1) SAND database flag
201
202
        edsdf 0
203
204
        nrest 90000
205
         nrunr 95000;
206
207
        c .... DYNA3D stent to compression cyl
208
209
        sid 1 dni
210
        c sfif
211
        c mfif
212
        pnlts 1.0e-0
213
        pnltm 1.0e-0
214
215
        С
216
        c .... DYNA3D tied interface to interconnects if multisegment
217
218
        if (%imodel.eq.0) then
219
        sid 2 tied
220
221
        endif
222
223
        c .... end DYNA3D commands
224
225
        endif
226
        С
227
            *** NIKE3D Analysis Options ***
228
229
        if (%inike.eq.1) then
230
         echo Making NIKE3D input file . . .
231
       nike3d
232
         nikeopts
233
234
        c .... temperatures follow load curve 1
235
            ** manually add tref=1.0 on matl 2 control card cols 26-35 **
        С
236
        С
237
         teo 1
238
239
        if (%isim_mode.eq.5) then
240
         anal dyn
241
         neig 20
242
         shift 69
243
         iplt 1
244
         nsbrr 1
245
         stifcore 1
```

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```
246
          bfgscore
                                                             FIG. 8F
247
          bwmo new
248
        c element constitutive data incore
249
250
251
          bfor 10
252
          sfor 10
253
          bef 11
254
255
        c .... linear solver
256
         Isolver fissle
257
258
259
        elseif (%isim_mode.ne.5) then
260
261
        c .... time step analysis
262
263
          nstep 100
          delt 0.0100
264
          anal stat
265
266
        c .... step tol of 1e-2 is OK for predel compression
267
268
        if (%isim_mode.eq.1.or.%isim_mode.eq.2) then
269
          dctol -1.0e-3
270
         elseif (%isim_mode.eq.3) then
271
          dctol -1.0e-2
272
         endif
273
274
         c .... max iterations per stiffness reform
275
276
          nibsr 20
277
278
 279
         c .... max stiffness reforms per step
 280
 281
           msrf 20;
         if (%isim_mode.eq.1.or.%isim_mode.eq.2) then
 282
 283
 284
         elseif (%isim_mode.eq.3.or.%isim_mode.eq.4) then
 285
           iprt 25
 286
         endif
 287
           iplt 1
 288
           nsbrr 1
 289
           stifcore 1
 290
           bfgscore
 291
           echo Bandwidth minimization ACTIVATED with "NEW" option
 292
 293
         c element constitutive data incore
 294
```

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```
295
                                                                  FIG. 8G
296
          bfor 10
          sfor 10
297
          bef 11
298
299
        c .... linear solver
300
301
         Isolver fissle
302
303
        c .... solid element stent contact surface
304
305
        sid 1 sv
306
307
        if (%isim_mode.eq.1) then
308
309
        c .... below changed for sharp-edge laser-cut stent
310
311
          pnlt 1.0e-3
312
         elseif (%isim_mode.eq.2) then
313
         pnlt 0.01
314
         elseif (%isim_mode.eq.3) then
315
316
         c .... essential to cut penalty for laser-cut stent predel compression
317
318
319
         pnlt 0.001
         elseif (%isim_mode.eq.4) then
320
          pnlt 1.0e-3
321
 322
         c iaug 1;
         endif
 323
 324
 325
         c .... end block for time step only analysis
 326
 327
 328
         endif
 329
         c .... slidesurface between interconnects and segments
 330
 331
         sid 2 tied
 332
 333
 334
         c .... slidesurface between stent and aortic wall
 335
 336
         if (%isim mode.eq.6) then
 337
         echo *** Add activation time of 0.5 to slidesurface 2 ***
 338
 339
         sid 3 sv
 340
         endif
 341
 342
          c .... NIKE3D shell geometric stiffness (HL only)
 343
```

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```
344
      ° C
                                                                      FIG. 8H
345
         segs 1;
346
        c .... end NIKE3D section
347
348
349
       endif
350
351
        c .... symmetry planes (omit for freq analysis)
352
353
        if (%isim mode.ne.5) then
354
        if (%isym.eq.1) then
355
356
        c .... Symmetric Model
357
358
        c plane 1
        c 0.0 0.0 0.0
359
360
        c [-\sin(60)][-\cos(60)] 0.0
361
            0.0005 symm;
362
        c plane 2
363
        c 0.0 0.0 0.0
364
        c [-\sin(60)][\cos(60)]0.0
365
            0.0005 symm;
366
        С
367
        else
368
        c .... symmetry planes to remove rigid body modes for full model
369
370
371
        plane 1
         0.0 0.0 0.0
372
373
         1.0 0.0 0.0
374
          .0005 symm;
375
        plane 2
376
         0.0 0.0 0.0
377
         0.0 1.0 0.0
378
          .0005 symm;
379
        endif
380
        endif
381
        С
382
383
        if (%inike.eq.0) then
384
        c .... Load Curves for DYNA3D **** ADD DR FLAG TO INPUT FILE ****
385
386
387
        if (%isim_mode.eq.1) then
388
389
        c .... radial force
390
391
        lcd 1
           0.000E+00 1.000E+00
392
```

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```
393
          7.500E-03 2.250E+02
                                                                  FIG. 8I
394
          1.000E-00 2.250E+02;
395
       elseif (%isim_mode.eq.2) then
396
397
       c .... flat plate compression, lcd 1 not used (dummy definition)
398
399
       echo!!! Flat plate not implemented for DYNA3D!!!
400
       quit
401
       elseif (%isim mode.eq.3) then
402
403
       c .... predelivery compression strain - 0.87 in. dia compressed to 12F
404
405
              [check x-displ of stent center node to verify]
406
407
       lcd 1
408
          0.000E+00 1.000E+00
409
          1.000E-02 1.008E+03
410
           1.000E-00 1.008E+03;
411
       elseif (%isim_mode.eq.6) then
412
413
       c .... anatomy deployment
414
            (LC from radial comp)
415
416
       lcd 1
417
          0.000E+00 1.000E+00
418
           7.500E-04 1.000E+03
419
          9.000E-04 1.000E+03
420
           1.500E-03 1.000E+00
421
           1.000E-00 1.000E+00;
422
       endif
423
424
       c .... load curve #2 only used for flat plate compression
425
426
       lcd 2
427
          0.000E+00 0.000E+00
428
          1.000E+00 0.000e-00;
429
       endif
430
431
       if (%inike.eq.1) then
432
       c .... ******* Load Curves for NIKE3D *******
433
434
435
       if (%isim_mode.eq.1) then
436
437
       c .... radial force
438
439
       lcd 1
440
           0.000E+00 1.000E+00
441
           1.000E+00 3.000E+02;
```

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```
442
        elseif (%isim mode.eq.2) then
                                                                          FIG. 8J
443
444
       c .... flat plate compression, lcd 1 not used (dummy definition)
445
446
       lcd 1
447
           0.000E+00 1.000E+00
448
           1.000E+00 0.000E+00;
449
        elseif (%isim mode.eq.3) then
450
451
        c .... predelivery compression strain - 0.87 in. dia compressed to 12F
              [check x-displ of stent center node to verify]
452
453
454
        lcd 1
455
           0.000E+00 1.000E+00
456
           1.000E+00 1.008E+03;
457
        elseif (%isim mode.eq.4) then
458
        c .... initial expansion strain - 4/5 mm OD to 15/27 mm OD
459
460
              [check x-displ of stent center node to verify]
461
        С
462
        lcd 1
463
        c .... thermal load (activate TEO above)
464
           0.000E+00 1.000E+00
465
           1.000E+00 -1.008E+03;
466
        c .... prescribed displacement
467
           0.000E+00 0.000E+00
468
           1.000E+00 1.000E-01;
        С
469
        elseif (%isim_mode.eq.5) then
470
471
        c .... must define load curve since TEO active even if unused for freq
472
473
474
        c .... initial expansion strain - 4/5 mm OD to 15/27 mm OD
475
              [check x-displ of stent center node to verify]
        С
476
        С
477
        lcd 1
478
        c .... thermal load (activate TEO above)
479
           0.000E+00 1.000E+00
480
           1.000E+00 -1.008E+03;
481
        elseif (%isim mode.eq.6) then
482
483
        c .... anatomy deployment - 0.87 in. dia compressed to 12F
484
        С
485
        lcd 1
486
           0.000E+00 1.000E+00
487
           0.500E+00 5.000E+02
488
           1.000E+00 1.000E+00;
489
        endif
490
        endif
```

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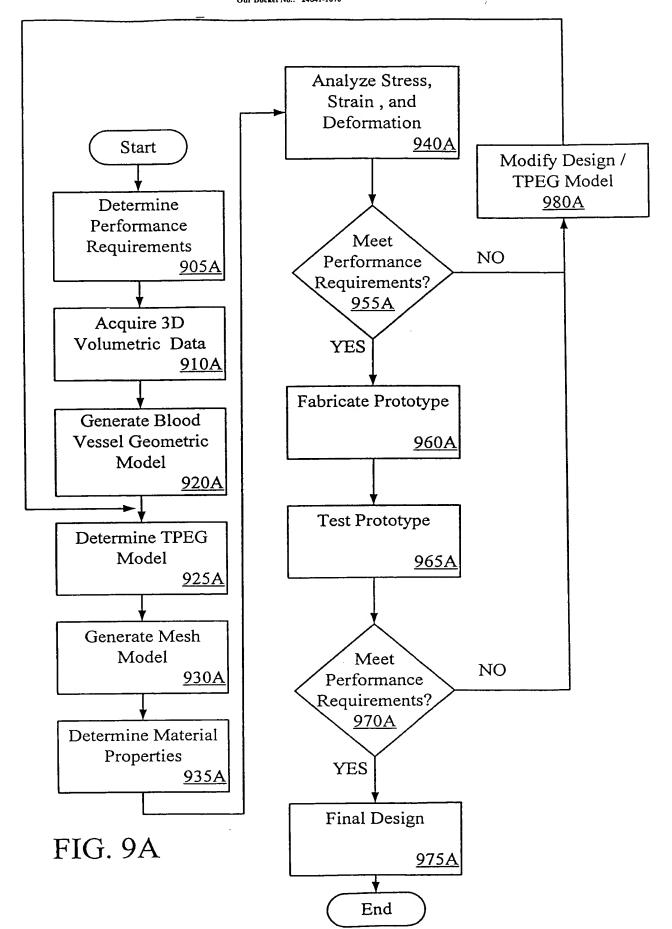
```
491
                                                                   FIG. 8K
492
       c ----- stent parts -----
493
494
       include irss.tg
495
496
       c ----- anatomy parts -----
497
498
       if (%isim mode.eq.6) then
499
500
       c .... convert anatomy data from cm to inch units
501
502
       control
503
       csca [1./2.54]
504
       c .... import meshed anatomy data for stent deployment
505
506
              (this is an aortic stent)
       С
507
508
       include tpeg.part_ct_aorta3
509
       csca 1.0
510
       merge
511
       if (%inike.eq.1) then
512
513
       c .... set material properties for aortic wall
514
515
       include aorta.materials nike
516
       endif
       endif
517
518
519
       c ----- stent materials -----
520
       if (%inike.eq.1) then
521
522
             if (%isim_mode.eq.1.or.%isim_mode.eq.2) then
               include istent.mats_nike_solid
523
524
               echo NiTi model for radial force/flat plate analysis
             elseif (%isim mode.eq.3) then
525
               include istent.mats_compress_nike_solid
526
               echo NiTi model for predelivery compression strain
527
528
             elseif (%isim_mode.eq.4) then
               include istent mats compress nike solid
529
530
               echo NiTi model for initial expansion strain
531
             elseif (%isim mode.eq.5) then
               include istent.mats_nike_freq_solid
532
               echo NiTi model for frequency analysis
533
             elseif (%isim_mode.eq.6) then
534
               include istent.mats_nike_solid
535
536
               echo NiTi model for anatomy deployment
537
             endif
538
        elseif (%inike.eq.0) then
539
```

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```
540
            if (%isim_mode.eq.1.or.%isim_mode.eq.2) then
                                                                            FIG. 8L
541
              include istent.mats dyna solid
542
              echo NiTi model for radial force/flat plate analysis
543
            elseif (%isim mode.eq.3) then
544
              include istent.mats_compress_dyna_solid
545
              echo NiTi model for predelivery compression strain
546
            elseif (%isim mode.eq.4) then
547
              include istent.mats_compress dyna solid
548
              echo NiTi model for initial expansion strain
549
            elseif (%isim_mode.eq.6) then
550
              include istent.mats_compress_dyna_solid
551
              echo NiTi model for anatomy deployment
552
            endif
553
      endif
554
555
      c .... cylindrical compression for radial force or predelivery compression
556
557
      if (%isim mode.eq.1.or.%isim_mode.eq.3.or.%isim_mode.eq.4.or.%isim_mode.eq.6) then
558
559
         if (%isym.eq.1) then
560
           include cylinder.parts sym
561
         else
562
           include cylinder.parts
563
         endif
564
         endif
565
566
      if (%inike.eq.1) then
567
        include cylinder.materials nike
568
      elseif (%inike.eq.0) then
569
        include cylinder.materials dyna
570
      endif
571
572
      stp .0001
573
574
      c .... Constrain stent node(s) in z-direction for time-hist analysis
575
576
      if (%isim mode.ne.5) then
577
      merge
578
579
      c .... nset for 3-segment model
580
      c nset zconstr = 18149 8687 9215 9747 ;
581
      c echo ** Bottom 12-crown node list Constrained in Z-translation **
582
583
      c .... nset for 6-crown only
584
      echo ** Bottom 6-crown node list constrained in z-dir **
585
      nset\ zconstr = 14397151448;
586
      b nset zconstr dz 1;
587
      endif
588
      С
```

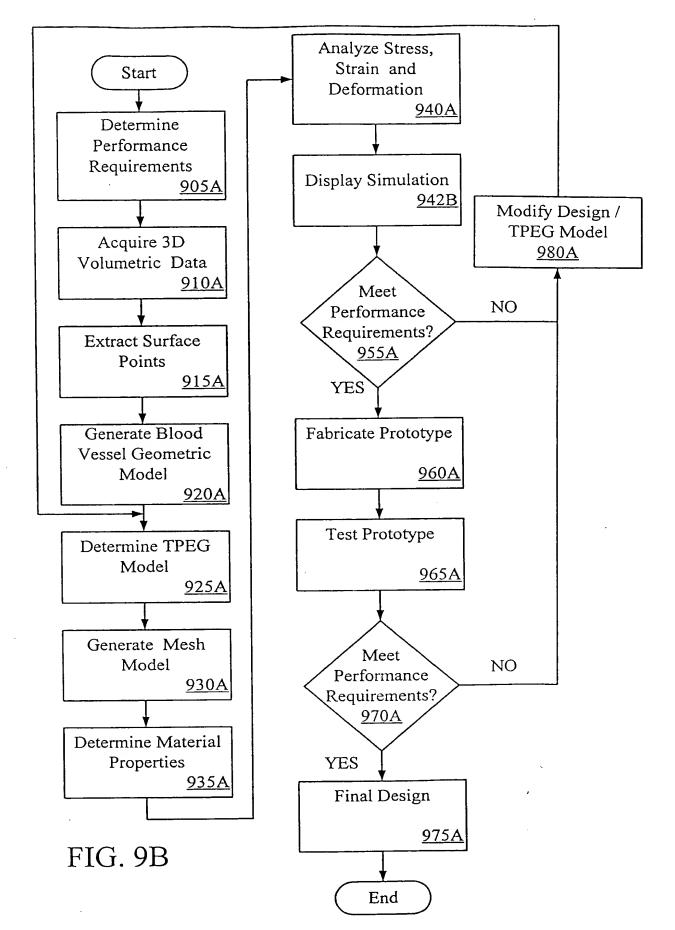
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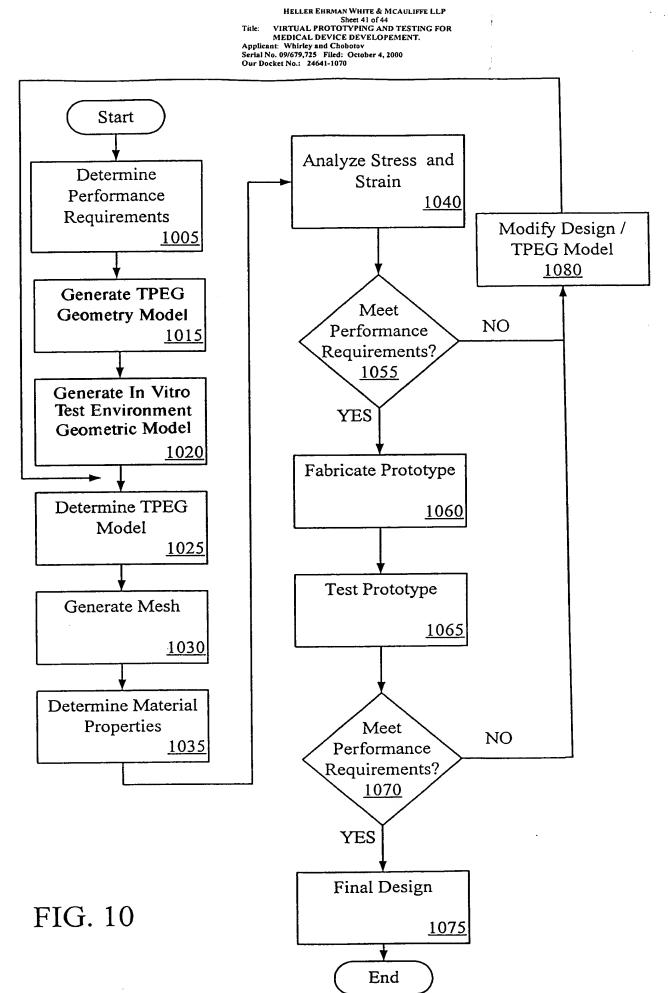


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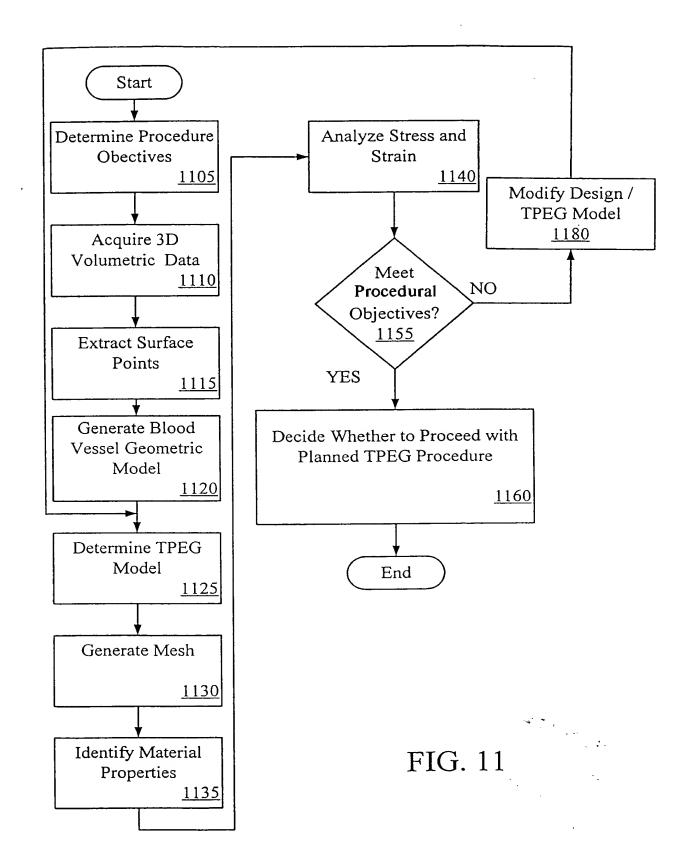




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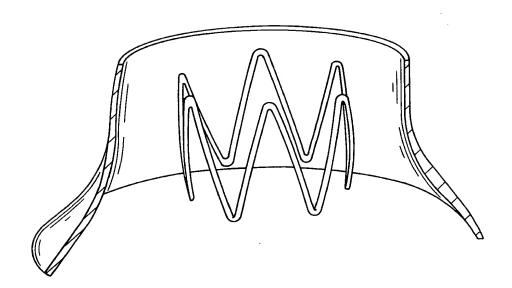


FIG. 12

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Our Docket No.: 24641-1070

FIG. 13

